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EDITION. Antenna

Azimuth Position

Control System

Antenna Potentiometer

Fixed field $e_m(t)$

Armature Gear Layout

Potentiometer $e_i(t)$

Desired azimuth angle

input Differential

amplifier and power

amplifier Motor

Schematic Desired

azimuth angle input

$e_i(t)$ n-turn

potentiometer 80 (t)

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Azimuth angle output

Differential

preamplifier Power

amplifier $v_p(t)$ $e_a(t)$

$V_i(t) + v_o(t) - kg\text{-m}^2$ N-

m s/rad V-s/rad N-m/A

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